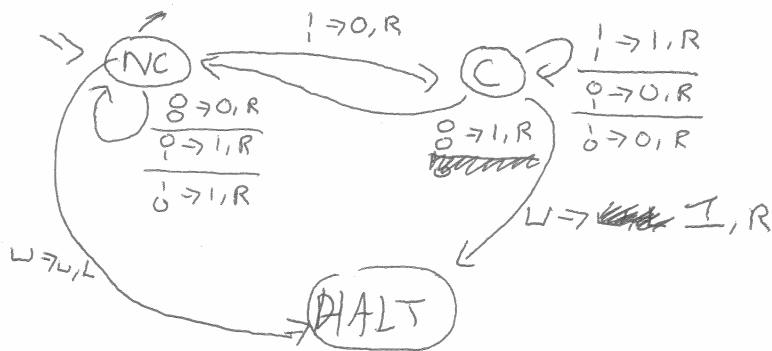


20-1/

$$\Sigma = \{0, 1, \bar{0}, \bar{1}\} \quad \Gamma = \{0, 1, \perp\} \cup \Sigma$$



DFA \Leftrightarrow REG

TM \Leftrightarrow Enumerator

PDA \Leftrightarrow CFG

DFA \Leftrightarrow NFA

(simple machine)

(complex)

Basic PL \Leftrightarrow Complicated PL

Stay Put TM

$$\delta: Q \times \Gamma \rightarrow Q \times \Gamma \times \{L, R\}$$

intuition + new

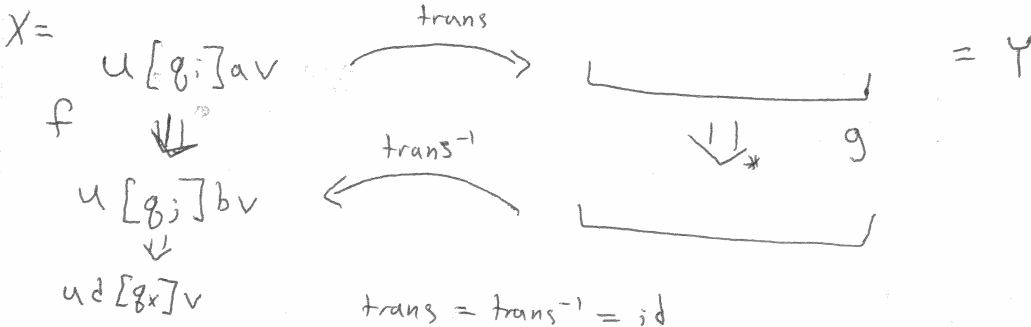
$$\delta': Q \times \Gamma \rightarrow Q \times \Gamma \times \{L, R, S\}$$

+ new semantics

$$\delta(q_i, a) = (q_j, b, S)$$

Galois

$$u[q_i]av \Rightarrow u[q_j]bv$$



$$\delta(q_i, a) = (q_k, b, R)$$

$$\delta(q_k, c) = (q_i, c, L)$$

$$u[q_i]acv \Rightarrow ub[q_k]cv \Rightarrow u[q_i]bcv$$

Translating from Stay to Normal: 1 state per S

1 extra step per S

20-2/

$$2-TM = (Q, \Sigma, \Gamma, q_0, \delta, q_a, q_r)$$

$$S : Q \times \Gamma \rightarrow Q \times \Gamma \times \{L, R\}$$

$$\begin{aligned} S' : Q \times \Gamma^2 &= Q \times \Gamma \times \Gamma \\ &\rightarrow Q \times (\Gamma \times \{L, R\})^2 \\ &= Q \times (\Gamma \times \{L, R\}) \times (\Gamma \times \{L, R\}) \end{aligned}$$

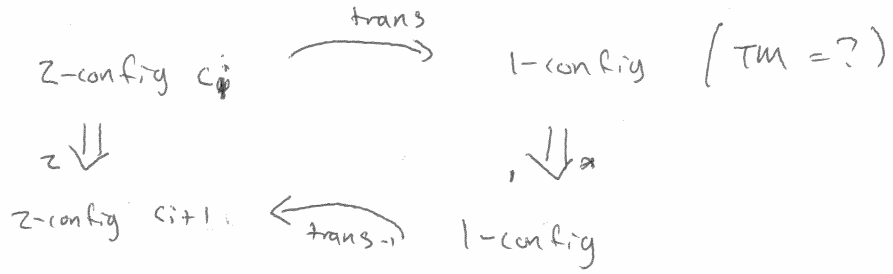
$$2\text{-config} = \begin{matrix} u \\ x \end{matrix} [q_i] \begin{matrix} v \\ y \end{matrix} \quad C_0 = \begin{matrix} \varepsilon \\ \varepsilon \end{matrix} [q_0] \begin{matrix} w \\ \varepsilon \end{matrix}$$

$\Rightarrow_2 \quad \Rightarrow_1$

$$\frac{S(q_i, b, B) = (q_j, (c, R), (r, L))}{\begin{matrix} ua \\ x\alpha \end{matrix} [q_i] \begin{matrix} bv \\ \beta y \end{matrix} \Rightarrow_2 \begin{matrix} uac \\ x \end{matrix} [q_j] \begin{matrix} v \\ \alpha r y \end{matrix}}$$

~~$S(q_i, a) \Rightarrow S(q_i, a)$~~

$$\begin{matrix} u \\ x \end{matrix} [q_i] \begin{matrix} v \\ y \end{matrix} \Rightarrow_2 \begin{matrix} u' \\ x' \end{matrix} [q_j] \begin{matrix} v' \\ y' \end{matrix} \quad \text{iff} \quad \begin{matrix} u \\ x \end{matrix} [q_i] \begin{matrix} v \\ y \end{matrix} \Rightarrow \begin{matrix} u' \\ x' \end{matrix} [q_j] \begin{matrix} v' \\ y' \end{matrix}$$



$$\begin{matrix} ua \\ x\alpha \end{matrix} [q_i] \begin{matrix} bv \\ \beta y \end{matrix} \xrightarrow{\text{trans}} \begin{matrix} ua \\ x\alpha \end{matrix} [\quad] \begin{matrix} bv \\ \beta y \end{matrix} \xrightarrow{\text{trans}} [q_i] \begin{matrix} ua \\ x\alpha \end{matrix} \begin{matrix} bv \\ \beta y \end{matrix}$$

$\Downarrow \rightarrow ???$

$$\begin{matrix} uac \\ x \end{matrix} [q_j] \begin{matrix} v \\ \alpha r y \end{matrix} \leftarrow [q_j] \begin{matrix} uac \\ x \end{matrix} \begin{matrix} v \\ \alpha r y \end{matrix}$$

$$q_i \xrightarrow{*} q_i/b \xrightarrow{*} q_i/b/B \xrightarrow{*} q_j/cR/rL \xrightarrow{\downarrow \alpha} q_j \xleftarrow{*} q_j/gold \xleftarrow{*} q_j/cR$$