

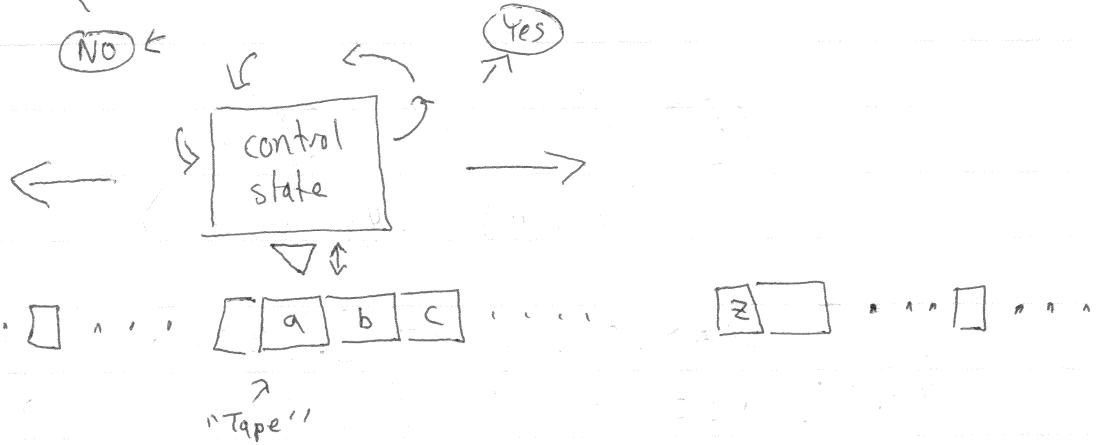
~~u-1~~
u-1

Turing Machines

DFA (control state [finite],
incremental viewing of input ("realtime")
"on line")

PDA (++ non-determinism
++ stack-based recall
- infinite space, but finite reach)

TM (-- non-determinism
++ infinite-space & infinite "reach"
-- online, kind of

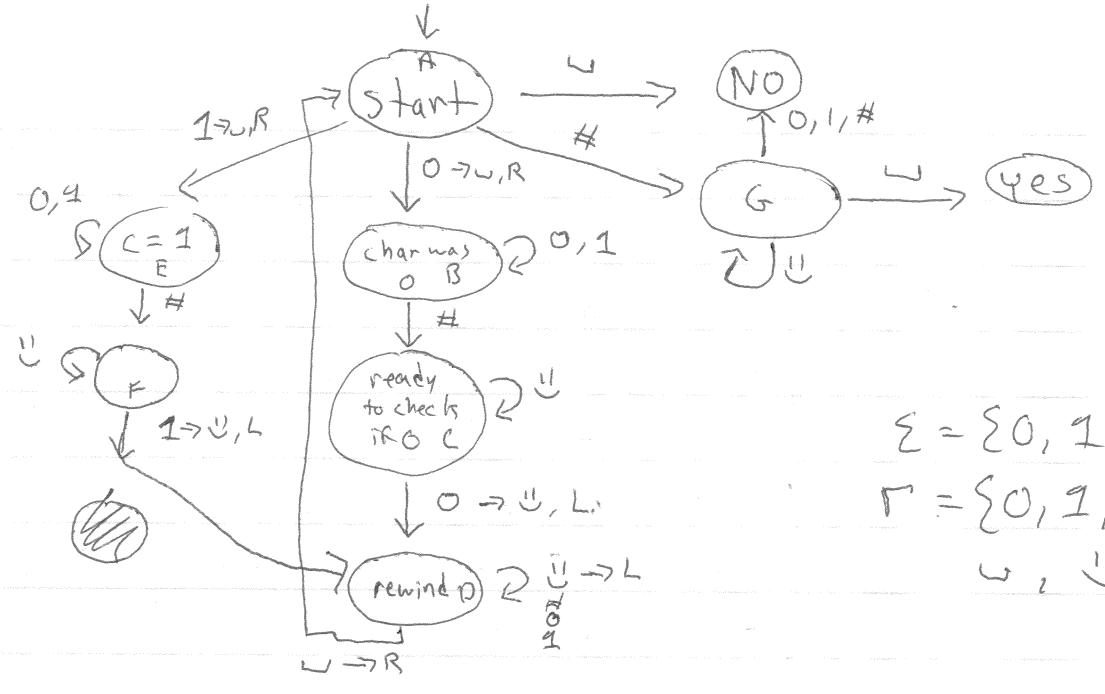


DFA $\delta: Q \times \Sigma \rightarrow Q$

PDA $\delta: Q \times \Sigma_e \times \Gamma_e \rightarrow P(Q \times \Gamma_e)$

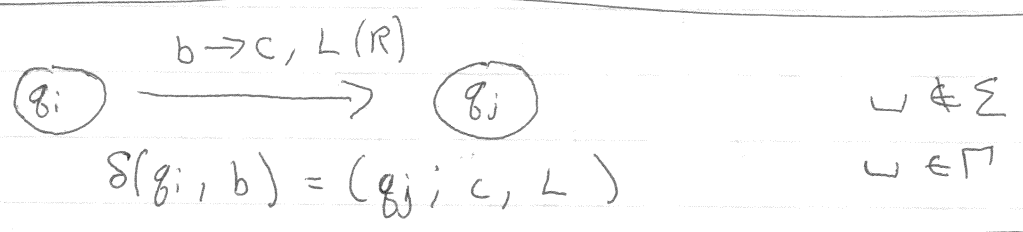
TM $\delta: Q \times \Gamma \rightarrow Q \times \Gamma \times \{L, R\} (\Sigma \subset \Gamma)$

$$B = \{ w \# w \mid w \in \{0,1\}^* \}$$



$$\Sigma = \{0, 1, \#\}$$

$$\Gamma = \{0, 1, \#, \epsilon, \sqcup\}$$



$\dots \sqcup [S] 010\#010 \sqcup \dots \Rightarrow [B] 10\#010 \Rightarrow 1[B] 0\#010 \Rightarrow$
 $10[B]\#010 \Rightarrow 10\#[C]010 \Rightarrow 10[D]\#\sqcup 10$
 $\Rightarrow \Rightarrow \Rightarrow [D] \sqcup 10\#\sqcup 10 \Rightarrow [S] 10\#\sqcup 10$
 $\Rightarrow [E] 0\#\sqcup 10 \Rightarrow \Rightarrow \Rightarrow 0\#\sqcup [F] 10$
 $\Rightarrow 0\#[D]\sqcup \sqcup 0 \Rightarrow \Rightarrow \Rightarrow [D] \sqcup 0\#\sqcup \sqcup 0$
 $\Rightarrow [S] 0\#\sqcup \sqcup 0 \Rightarrow^a [D] \sqcup \#\sqcup \sqcup \sqcup$
 $\Rightarrow [S] \#\sqcup \sqcup \sqcup \Rightarrow \#[G] \sqcup \sqcup \sqcup \Rightarrow^b \#\sqcup \sqcup \sqcup [G] \sqcup$
 $\Rightarrow \text{YES}$