## From Bayesian Notation to Pure Racket

via Discrete Measure-Theoretic Probability in $\lambda_{\text {zFC }}$

Implementation and Application of Functional Languages
September 1-3, 2010

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PLT @ Brigham Young University, Utah, USA

## Bayesian Practice and Philosophy

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John Wilder Tukey
"An approximate answer to the right question is worth a great deal more than a precise answer to the wrong question."

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Model and query

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\(\mathbf{S}_{i, j}^{\boldsymbol{\theta}} \sim \mathrm{Uniform}(-\pi, \pi) \quad \mathbf{S}_{i, j}^{\mathbf{v}^{+}} \sim \operatorname{Uniform}(0,1)\)
\(\mathbf{S}_{i, j}^{d} \sim \operatorname{Uniform}(-3,3) \quad \mathbf{S}_{i, j}^{-} \sim \operatorname{Uniform}(0,1)\)
\(\mathrm{S}_{i, j}^{\sigma} \sim \operatorname{Beta}(1.6,1)\)
    \(\mathbf{I}_{i, j} \mid \mathbf{S}_{\mathrm{N} 9(t, j)} \sim \operatorname{Normal}\left(\mathbf{E}\left[\mathbf{S}_{i, j}\right], \omega\right)\)
    \(\boldsymbol{\Phi}_{i, j}\left(\mathbf{S}_{\mathrm{N} 9(i, j)}\right) \equiv \exp \left(-\frac{\operatorname{Var}\left[\mathrm{S}_{i, j}\right]}{2 \gamma^{2}}\right)\)
```

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& \mathbf{S}_{i, j}^{e} \sim \operatorname{Beta}(1.6,1) \\
& \quad \mathbf{I}_{i, j} \mid \mathbf{S}_{\mathrm{N} 9(i, j)} \sim \operatorname{Uniform}(0,1) \\
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What is the distribution of $\mathbf{I} \mid \mathbf{I}$ ?

The answer's approximation


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- Our motivation: free (fire?) the grad students
- Our primary constraints
- Do not approximate earlier than users would
- Do not force users to approximate early


## Philosophical Constraints

- Compatible approach

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- Analogous to abstract interpretation
concrete/exact, abstract/approximating


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- Calculations uncomputable when $\Omega$ infinite


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$\lambda$ calculus
$(\lambda x, e, x, e e), \alpha, \beta)$


Set theory
$(V, \in,=,\{r\}, \bigcup$, image, $\mathcal{P}$, order $)$

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- "Programming" is doing contemporary math, plus $\lambda x . e$
- Contains all set-theoretic functions
- Can solve any OTM halting problem constructively


| Interpreting Notation | Computational <br> Syntactic <br> Category | Examples |
| :---: | :---: | :---: |

Developing the whole semantics right now would take too much time, so l'm going to give some examples of syntax and talk about the structure of the calculations.

First we have random variable expressions. In the first example, X and Y are random variables, so they're functions of Omega. I've already hinted that you could interpret this by regarding andom variables as reader monad computations.

But there's no reason to impose a total order, so we use the corresponding applicative functor, or idiom.

Next, we have statements about random variables. A collection of statements is a probabilistic model. We interpret each statement as transforming the global probability space. The first example, X is distributed Geometric B, extends the probability space. The second example is a 'condition,' which asserts that applying the random variable $\mathrm{X}+\mathrm{Y}$ to any world must yield 4. It *restricts* the global probability space.

A nice way to structure these calculations is with the state monad, with probability-space-valued state

Last, we have queries. The first example is a `conditional probability query'. It conditions the probability space first, and then asks for the probability that $B$ outputs $1 / 2$. The second example is like the first, but is parameterized on the outputs of B and $\mathrm{X}+\mathrm{Y}$. It should return a function, or a distribution, so it's a 'distribution query'.
Queries run the probability space monad computation in their own particular way.

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| Queries | $\begin{aligned} & \mathbf{P}\left[\left.B=\frac{1}{2} \right\rvert\, X+Y=4\right] \\ & \mathcal{C}[B \mid X+Y] \end{aligned}$ | State monad run: $\begin{aligned} & b=[0,1] \text { or } \\ & b=a \rightarrow c \rightarrow[0,1] \end{aligned}$ | $\begin{aligned} & \mathbf{P} \llbracket \rrbracket, \mathbf{D} \llbracket \cdot \rrbracket \text {, } \\ & \text { Pr, Dist } \end{aligned}$ |

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State monad run:
$b=[0,1]$ or
$\mathbf{P} \llbracket \cdot \rrbracket, \mathbf{D} \llbracket \rrbracket]$,
$b=a \rightarrow c \rightarrow[0,1]$

- Difficult to encode types in most type systems



## Fun Facts: Semantics

$-\mathcal{R}[\cdot]: \lambda_{\text {ZFC }} \rightarrow \lambda_{\text {ZFC }}$ interprets anything constructive

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- Uncountable $\Omega$ : need to prove measurability conditions
- $\mathcal{R}[\operatorname{Geometric}(B)]: \Omega \rightarrow \mathbb{N} \rightarrow[0,1]$ is a discrete transition kernel
- Uncountable $\Omega$ already works: $\mathcal{R} \llbracket \operatorname{Normal}(M, S) \rrbracket: \Omega \rightarrow \mathcal{B}(\mathbb{R}) \rightarrow[0,1]$
- Queries approximate with finitize $(\Omega, P) k=\left(\Omega_{k}, P_{k}\right)$
- Uncountable $\Omega$ : finitize $(\Omega, \Sigma, \mathbb{P}) k=\left(\Omega_{k}, P_{k}\right)$ with $\Omega_{k}$ finite, stochastic


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- (define-model name [X ~ ...] ...) is hygienically referred to by (with-model name (Pr ... X ...))


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    (define (p1-fires? n [shots 1])
    (cond [(<= n 0) #f]
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## Duelling Idiot and Half-Wit

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(define-model half-wit-duel
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(Pr spin? (not (p1-fires? winning-shot))))
Answer: about 0.588 (compare (Pr spin?) $=0.5$ )

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- Variable collapse (constant folding for rvs)

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X \sim \operatorname{Normal}(0,1) ; Y \sim \operatorname{Normal}(X, 1) \longrightarrow Y \sim \operatorname{Normal}(0,2)
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- Propagating conditions (like constraint propagation)

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- Justifiable only in the exact semantics


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- Model equivalence: $m \equiv \mathbf{D} m^{\prime}$ means no query $q$ can distinguish between $m$ and $m^{\prime}$
- Justifies measure-theoretic optimizations
- Variable collapse (constant folding for rvs)

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X \sim \operatorname{Normal}(0,1) ; Y \sim \operatorname{Normal}(X, 1) \longrightarrow Y \sim \operatorname{Normal}(0,2)
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- Propagating conditions (like constraint propagation)

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